

REVISITING SIMULATION FUNCTIONS VIA INTERPOLATIVE CONTRACTIONS

Erdal Karapınar

This paper is dedicated to Professor Gradimir V. Milovanovic on the occasion of his 70th anniversary.

In this paper, introduce the notion of an interpolative Hardy-Rogers type \mathcal{Z} -contraction and we revisit the renowned Hardy-Rogers contraction in the framework of interpolation. We investigate the existence of fixed points for such mappings in the context of metric spaces and list immediate consequences that covers some existing results in the literature.

1. Introduction and Preliminaries

In 2015 Khojasteh *et al.* [16], introduced an auxiliary function, *simulation function*, that covers and involves several existing contraction types in the literature. On the other hand, very recently, in [14], an interpolative contraction mappings are introduced to enrich fixed point theory. Interpolation theory is very deep theory and has been used widely in several research fields, see e.g. [17]. In this paper, we want to combine these two approaches and investigate the existence of fixed points that forms interpolative contractions in the framework of simulation functions in the context of complete metric spaces.

First of all, for the sake of completeness we recollect some basic definitions and results.

Definition 0.1. (See [16]) *A simulation function is a mapping $\zeta : [0, \infty) \times [0, \infty) \rightarrow \mathbb{R}$ satisfying the following conditions:*

2010 Mathematics Subject Classification. 46T99, 47H10; 54H25.
Keywords and Phrases. Simulation Function, Fixed Point, Metric Space

(ζ_1) $\zeta(t, s) < s - t$ for all $t, s > 0$;

(ζ_2) if $\{t_n\}, \{s_n\}$ are sequences in $(0, \infty)$ such that $\lim_{n \rightarrow \infty} t_n = \lim_{n \rightarrow \infty} s_n > 0$, then

$$(1) \quad \limsup_{n \rightarrow \infty} \zeta(t_n, s_n) < 0.$$

(ζ_3) $\zeta(0, 0) = 0$;

Due to the axiom (ζ_1), we have

$$(2) \quad \zeta(t, t) < 0 \text{ for all } t > 0.$$

The definition above was refined by omitting the condition $\zeta(0, 0) = 0$ Argoubi *et al.* [4]. Throughout the paper, the letter \mathcal{Z} denotes the family of all functions $\zeta : [0, \infty) \times [0, \infty) \rightarrow \mathbb{R}$ that satisfies only (ζ_1) and (ζ_2). From now on, a function ζ is called simulation function if $\zeta \in \mathcal{Z}$.

The following example is derived from [1].

Example 0.1. Let $\phi_i : [0, \infty) \rightarrow [0, \infty)$ be continuous functions such that $\phi_i(t) = 0$ if and only if, $t = 0$. For $i = 1, 2, 3, 4, 5, 6$, we define the mappings $\zeta_i : [0, \infty) \times [0, \infty) \rightarrow \mathbb{R}$, as follows

(i) $\zeta_1(t, s) = \phi_1(s) - \phi_2(t)$ for all $t, s \in [0, \infty)$, where $\phi_1, \phi_2 : [0, \infty) \rightarrow [0, \infty)$ are two continuous functions such that $\phi_1(t) = \phi_2(t) = 0$ if and only if $t = 0$ and $\phi_1(t) < t \leq \phi_2(t)$ for all $t > 0$.

(ii) $\zeta_2(t, s) = s - \frac{f(t, s)}{g(t, s)}t$ for all $t, s \in [0, \infty)$, where $f, g : [0, \infty)^2 \rightarrow (0, \infty)$ are two continuous functions with respect to each variable such that $f(t, s) > g(t, s)$ for all $t, s > 0$.

(iii) $\zeta_3(t, s) = s - \phi_3(s) - t$ for all $t, s \in [0, \infty)$.

(iv) $\zeta_4(t, s) = s\varphi(s) - t$ for all $s, t \in [0, \infty)$, where $\varphi : [0, \infty) \rightarrow [0, 1)$ is a function such that $\limsup_{t \rightarrow r^+} \varphi(t) < 1$ for all $r > 0$.

(v) $\zeta_5(t, s) = \eta(s) - t$ for all $s, t \in [0, \infty)$, where $\eta : [0, \infty) \rightarrow [0, \infty)$ is an upper semi-continuous mapping such that $\eta(t) < t$ for all $t > 0$ and $\eta(0) = 0$.

(vi) $\zeta_6(t, s) = s - \int_0^t \phi(u)du$ for all $s, t \in [0, \infty)$, where $\phi : [0, \infty) \rightarrow [0, \infty)$ is a function such that $\int_0^\varepsilon \phi(u)du$ exists and $\int_0^\varepsilon \phi(u)du > \varepsilon$, for each $\varepsilon > 0$.

It is clear that each function ζ_i ($i = 1, 2, 3, 4, 5, 6$) forms a simulation function.

One can find more interesting examples of simulation functions in [1–3, 5, 11–13, 16, 18].

Suppose (X, d) is a metric space, T is a self-mapping on X and $\zeta \in \mathcal{Z}$. We say that T is a \mathcal{Z} -contraction with respect to ζ [16], if

$$(3) \quad \zeta(d(Tx, Ty), d(x, y)) \geq 0 \quad \text{for all } x, y \in X.$$

Again (ζ_2) , we have the following inequality

$$(4) \quad d(Tx, Ty) \neq d(x, y) \text{ for all distinct } x, y \in X.$$

Thus, we conclude that T cannot be an isometry whenever T is a \mathcal{Z} -contraction. In other words, if a \mathcal{Z} -contraction T in a metric space has a fixed point, then it is necessarily unique.

Theorem 0.1. *Every \mathcal{Z} -contraction on a complete metric space has a unique fixed point.*

Recently an interesting fixed point result via interpolation was reported in [14]. More precisely, in [14], the notion of interpolative Kannan contraction was introduced as follows: For a metric space (X, d) , a mapping $T : X \rightarrow X$ is called an interpolative Kannan contraction if

$$(5) \quad d(Tx, Ty) \leq \lambda [d(x, Tx)]^\alpha \cdot [d(y, Ty)]^{1-\alpha},$$

for all $x, y \in X$ with $x, y \in X \setminus \text{Fix}(T)$, where $\text{Fix}(T)$ is the set of all fixed point of T , $\lambda \in [0, 1)$ and $\alpha \in (0, 1)$. The main result in [14] is the following.

Theorem 0.2 ([14]). *Let (X, d) be a complete metric space and T be an interpolative Kannan type contraction. Then T has a fixed point in X .*

For sake of completeness, we shall recollect one of the renowned generalizations of the Banach Contraction Principle [6] which is know as Hardy-Rogers contraction:

Theorem 0.3. [8]. *Let (X, d) be a complete metric space. Let $T : X \rightarrow X$ be a given mapping such that*

$$d(Tx, Ty) \leq \alpha d(x, y) + \beta d(x, Tx) + \gamma d(y, Ty) + \delta \left[\frac{1}{2}(d(x, Ty) + d(y, Tx)) \right],$$

for all $x, y \in X$, where $\alpha, \beta, \gamma, \delta$ are non-negative reals such that $\alpha + \beta + \gamma + \delta < 1$. Then T has a unique fixed point in X .

In this paper, we investigate interpolative type contractions by using the simulation function in the context of complete metric spaces. More precisely, we revisit the renowned Hardy-Rogers contraction in the framework of interpolation via simulation function.

2. Main results

We start with the following definition that is belong to Browder and Petrusyn [7].

Definition 0.2. We say that a self-mapping $T : X \rightarrow X$ on a metric space (X, d) is asymptotically regular at a point $x \in X$ if $\lim_{n \rightarrow \infty} d(T^n x, T^{n+1} x) = 0$

On what follows we introduce the notion of the interpolative Hardy-Rogers type \mathcal{Z} -contraction.

Definition 0.3. Let T be a self-mapping defined on a metric space (X, d) . If there exist $\alpha, \beta, \gamma \in (0, 1)$ with $\alpha + \beta + \gamma < 1$, and $\zeta \in \mathcal{Z}$ such that

$$(6) \quad \zeta(d(Tx, Ty), C(x, y)) \geq 0,$$

for all $x, y \in X \setminus \text{Fix}(T)$, where $\text{Fix}(T)$ is the set of all fixed point of T , and

$$C(x, y) := [d(x, y)]^\beta \cdot [d(x, Tx)]^\alpha \cdot [d(y, Ty)]^\gamma \cdot \left[\frac{1}{2}(d(x, Ty) + d(y, Tx)) \right]^{1-\alpha-\beta-\gamma}$$

then we say that T is an interpolative Hardy-Rogers type \mathcal{Z} -contraction with respect to ζ .

Lemma 0.1. On a metric space (X, d) , every Hardy-Rogers type \mathcal{Z} -contraction with respect to ζ is asymptotically regular

Proof. Let x be an arbitrary point of a metric space (X, d) and let $T : X \rightarrow X$ be a Hardy-Rogers type \mathcal{Z} -contraction with respect to $\zeta \in \mathcal{Z}$. If there exists some $p \in \mathbb{N}$ such that $T^p x = T^{p-1} x$, then $y = T^{p-1} x$ is a fixed point of T , that is, $Ty = y$. Consequently, we have that $T^n y = y$ for all $n \in \mathbb{N}$, so

$$\begin{aligned} d(T^n x, T^{n+1} x) &= d(T^{n-p+1} T^{p-1} x, T^{n-p+2} T^{p-1} x) = d(T^{n-p+1} y, T^{n-p+2} y) \\ &= d(y, y) = 0, \end{aligned}$$

for sufficient large $n \in \mathbb{N}$. Thus, we conclude that

$$\lim_{n \rightarrow \infty} d(T^n x, T^{n+1} x) = 0.$$

So T is asymptotically regular at x . On the contrary, suppose that $T^n x \neq T^{n-1} x$ for all $n \in \mathbb{N}$, that is,

$$d(T^n x, T^{n-1} x) > 0 \quad \text{for all } n \in \mathbb{N}.$$

On what follows, from (6) and (ζ_1) , we have that, for all $n \in \mathbb{N}$,

$$0 \leq \zeta(d(T^{n+1} x, T^n x), C(T^n x, T^{n-1} x)) < C(T^n x, T^{n-1} x) - d(T^{n+1} x, T^n x).$$

In particular,

$$(7) \quad d(T^{n+1} x, T^n x) < C(T^n x, T^{n-1} x) \quad \text{for all } n \in \mathbb{N}, \text{ where}$$

$$\begin{aligned}
(8) \quad C(T^n x, T^{n-1} x) &= [d(T^n x, T^{n-1} x)]^\beta \cdot [d(T^n x, T^{n+1} x)]^\alpha \cdot [d(T^{n-1} x, T^n x)]^\gamma \\
&\quad \cdot \left[\frac{1}{2} (d(T^n x, T^n x) + d(T^{n-1} x, T^{n+1} x)) \right]^{1-\alpha-\beta-\gamma} \\
&\leq [d(T^n x, T^{n-1} x)]^\beta \cdot [d(T^n x, T^{n+1} x)]^\alpha \cdot [d(T^{n-1} x, T^n x)]^\gamma \\
&\quad \cdot \left[\frac{1}{2} (d(T^{n-1} x, T^n x) + d(T^n x, T^{n+1} x)) \right]^{1-\alpha-\beta-\gamma}.
\end{aligned}$$

Note that for the assumption $d(T^{n-1} x, T^n x) < d(T^n x, T^{n+1} x)$, the expression (7) turns into

$$(9) \quad C(T^n x, T^{n-1} x) \leq [d(T^n x, T^{n-1} x)]^\beta \cdot [d(T^n x, T^{n+1} x)]^\alpha \cdot [d(T^{n-1} x, T^n x)]^\gamma \cdot [d(T^n x, T^{n+1} x)]^{1-\alpha-\beta-\gamma}.$$

Thus, the inequality (7) together with (9) yields that

$$(10) \quad [d(T^n x, T^{n+1} x)]^{\beta+\gamma} < [d(T^{n-1} x, T^n x)]^{\beta+\gamma}.$$

It is a contradiction with assumption. Hence, we have

$$d(T^{n-1} x, T^n x) < d(T^n x, T^{n+1} x) \text{ for all } n \in \mathbb{N}$$

On account of the inequality above, we deduce that the sequence $\{d(T^n x, T^{n-1} x)\}$ is a monotonically decreasing of non-negative real numbers. Thus, there exists $\ell \in [0, \infty)$ such that $\lim_{n \rightarrow \infty} d(T^n x, T^{n+1} x) = \ell \geq 0$. We shall prove that $\ell = 0$. Suppose, on the contrary, that $\ell > 0$. It is easy to see that $\lim_{n \rightarrow \infty} C(T^n x, T^{n+1} x) = \ell$.

Since T is Hardy-Rogers type \mathcal{Z} -contraction with respect to $\zeta \in \mathcal{Z}$, by (ζ_2) , we have

$$0 \leq \limsup_{n \rightarrow \infty} \zeta(d(T^{n+1} x, T^n x), C(T^n x, T^{n-1} x)) < 0,$$

which is a contradiction. Thus, $\ell = 0$ and this proves that

$$\lim_{n \rightarrow \infty} d(T^n x, T^{n+1} x) = 0.$$

Hence, T is an asymptotically regular mapping at x . \square

Remark 0.1. *In the proof of the previous result we have proved that if $T : X \rightarrow X$ is a Hardy-Rogers type \mathcal{Z} -contraction on a metric space (X, d) and $\{x_{n+1} = T^n x_0\}$ is a Picard sequence of T , then*

$$(11) \quad \begin{aligned}
&\text{either there exists } k_0 \in \mathbb{N} \text{ such that } x_{k_0} \text{ is a fixed point of } T \\
&\text{or } 0 < d(T^{n+1} x, T^n x) < d(T^n x, T^{n-1} x) \quad \text{for all } n \in \mathbb{N}.
\end{aligned}$$

Now, we show that every Picard sequence $\{x_n\}$ generated by a Hardy-Rogers type \mathcal{Z} -contraction is always bounded.

Lemma 0.2. *Let a self-mapping T on a metric space (X, d) form a Hardy-Rogers type \mathcal{Z} -contraction with respect to ζ . If $\{x_n\}$ is a Picard sequence generated by T , then $\{d(x_n, x_m) : n, m \in \mathbb{N}\}$ is bounded.*

Proof. Start with an arbitrary initial point $x_0 \in X$ we built a iterative sequence $\{x_n\}$ which is defined recursively by $x_{n+1} = Tx_n$ for all non-negative integer n . If there exists some $n \geq 0$ and $p \geq 1$ such that $x_{n+p} = x_n$, then the set $\{x_n : n \in \mathbb{N}\}$ is finite, so it is bounded. Hence, assume that $x_{n+p} \neq x_n$ for all $n \geq 0$ and $p \geq 1$. In this case, by Remark 0.1, we have that:

$$(12) \quad 0 < d(x_{n+1}, x_n) < d(x_n, x_{n-1}) \quad \text{for all } n \in \mathbb{N}.$$

Notice that by Lemma 0.1,

$$(13) \quad \lim_{n \rightarrow \infty} d(x_{n+1}, x_n) = 0.$$

In particular, there exists $n_0 \in \mathbb{N}$ such that

$$d(x_{n+1}, x_n) < 1 \quad \text{for all } n \geq n_0.$$

We shall prove that $\{x_n : n \in \mathbb{N}\}$ is bounded by the method of *Reductio ad Absurdum*. We assume that the set

$$D = \{d(x_m, x_n) : m > n\}.$$

is not bounded. Thus, one can find a subsequence $\{x_{n_k}\}$ of $\{x_n\}$ such that $\lim_{k \rightarrow \infty} d(x_{n_{k+1}}, x_{n_k}) \neq 0$. Indeed, since D is unbounded, there exist n_1, n_0 with $n_1 > n_0$ such that $d(x_{n_1}, x_{n_0}) > 1$. If n_1 is the smallest natural number, greater than n_0 , verifying this property, then we can suppose that

$$d(x_p, x_{n_0}) \leq 1 \quad \text{for all } p \in \{n_0, n_0 + 1, \dots, n_1 - 1\}.$$

Again, as D is not bounded, there exists $n_2 > n_1$ such that

$$d(x_{n_2}, x_{n_1}) > 1 \quad \text{and} \quad d(x_p, x_{n_1}) \leq 1 \quad \text{for all } p \in \{n_1, n_1 + 1, \dots, n_2 - 1\}.$$

Recursively, we can get a partial subsequence $\{x_{n_k}\}$ of $\{x_n\}$ such that, for all $k \geq 1$,

$$d(x_{n_{k+1}}, x_{n_k}) > 1 \quad \text{and} \quad d(x_p, x_{n_k}) \leq 1 \quad \text{for all } p \in \{n_k, n_k + 1, \dots, n_{k+1} - 1\}.$$

Hence, by the triangular inequality, we have that, for all k ,

$$(14) \quad 1 < d(x_{n_{k+1}}, x_{n_k}) \leq d(x_{n_{k+1}}, x_{n_{k+1}-1}) + d(x_{n_{k+1}-1}, x_{n_k}) \leq d(x_{n_{k+1}}, x_{n_{k+1}-1}) + 1.$$

Letting $k \rightarrow \infty$ in (14) and taking (13) into account, we obtain

$$\lim_{k \rightarrow \infty} d(x_{n_{k+1}}, x_{n_k}) = 1.$$

By (12), we have $d(x_{n_{k+1}}, x_{n_k}) \leq d(x_{n_{k+1}-1}, x_{n_k-1})$. Therefore using the triangular inequality we obtain

$$\begin{aligned} 1 < d(x_{n_{k+1}}, x_{n_k}) &\leq d(x_{n_{k+1}-1}, x_{n_k-1}) \leq d(x_{n_{k+1}-1}, x_{n_k}) + d(x_{n_k}, x_{n_k-1}) \\ &\leq 1 + d(x_{n_k}, x_{n_k-1}). \end{aligned}$$

Letting $k \rightarrow \infty$ and using (13) we obtain

$$\lim_{k \rightarrow \infty} d(x_{n_{k+1}-1}, x_{n_k-1}) = 1.$$

Since T is a Hardy-Rogers type \mathcal{Z} -contraction with respect to $\zeta \in \mathcal{Z}$, for all k , we have

$$0 \leq \zeta(d(Tx_{n_{k+1}-1}, Tx_{n_k-1}), C(x_{n_{k+1}-1}, x_{n_k-1})) < C(x_{n_{k+1}-1}, x_{n_k-1}) - d(x_{n_{k+1}}, x_{n_k})$$

which is equivalent to

$$(15) \quad d(x_{n_{k+1}}, x_{n_k}) < C(x_{n_{k+1}-1}, x_{n_k-1}),$$

where

$$\begin{aligned} C(x_{n_{k+1}-1}, x_{n_k-1}) &= [d(x_{n_{k+1}-1}, x_{n_k-1})]^\beta \cdot [d(x_{n_{k+1}-1}, Tx_{n_{k+1}-1})]^\alpha \\ &\quad \cdot [d(x_{n_k-1}, Tx_{n_k-1})]^\gamma \\ &\quad \cdot \left[\frac{1}{2}(d(x_{n_{k+1}-1}, Tx_{n_k-1}) + d(x_{n_k-1}, Tx_{n_{k+1}-1})) \right]^{1-\alpha-\beta-\gamma}. \end{aligned}$$

Letting $k \rightarrow \infty$ in the inequality (15), we find that

$$(16) \quad 1 = \lim_{k \rightarrow \infty} d(x_{n_{k+1}}, x_{n_k}) \leq 0$$

is a contradiction. This proves that $D = \{d(x_m, x_n) : m > n\}$ is bounded. \square

We can now state the main result of this paper.

Theorem 0.4. *Let (X, d) be a complete metric space and T be an interpolative Hardy-Rogers type \mathcal{Z} -contraction with respect to ζ . Then there exists $u \in X$ such that $Tu = u$.*

Proof. Start with an arbitrary initial point $x_0 \in X$, we construct the Picard sequence $\{x_n = T^n x_0\}_{n \geq 0}$. In case of a sequence $\{x_n\}$ contains a fixed point of T , the proof is completed. So, we assume that $\{x_n\}$ has no fixed point of T . Accordingly, due to Lemma 0.1 together with Remark 0.1 we derive that

$$(17) \quad 0 < d(x_{n+1}, x_n) < d(x_n, x_{n-1}) \quad \text{for all } n \in \mathbb{N}.$$

$$(18) \quad \lim_{n \rightarrow \infty} d(x_{n+1}, x_n) = 0.$$

We assert that the sequence $\{x_n\}$ is Cauchy. On account that Lemma 0.2, we guarantee that $\{d(x_m, x_n) : m, n \in \mathbb{N}\}$ is bounded. Consider the sequence $\{S_n\} \subset [0, \infty)$ given by:

$$S_n = \sup(\{d(x_i, x_j) : i \geq j \geq n\}) \quad \text{for all } n \in \mathbb{N}.$$

It is easy to notice that the sequence $\{S_n\}$ is a monotonically non-increasing of non-negative real numbers. Thus, we conclude that this sequence is convergent,

that is, there exists $S \geq 0$ such that $\lim_{n \rightarrow \infty} S_n = S$. We claim that $S = 0$. We shall use the method of *Reductio ad Absurdum* to prove our claim. Suppose, on the contrary, that $S > 0$. Then, by definition of S_n , for every $k \in \mathbb{N}$ there exists $n_k, m_k \in \mathbb{N}$ such that $m_k > n_k \geq k$ and

$$S_k - \frac{1}{k} < d(x_{m_k}, x_{n_k}) \leq S_k.$$

Hence, we find

$$(19) \quad \lim_{k \rightarrow \infty} d(x_{m_k}, x_{n_k}) = S.$$

By using (17) and the triangular inequality, we have, for all k ,

$$d(x_{m_k}, x_{n_k}) \leq d(x_{m_k-1}, x_{n_k-1}) \leq d(x_{m_k-1}, x_{m_k}) + d(x_{m_k}, x_{n_k}) + d(x_{n_k}, x_{n_k-1}).$$

Letting $k \rightarrow \infty$ in the above inequality and using (18) and (19), we derive that

$$(20) \quad \lim_{k \rightarrow \infty} d(x_{m_k-1}, x_{n_k-1}) = S.$$

Hence, we have Due to fact that T is a Hardy-Rogers type \mathcal{Z} -contraction with respect to $\zeta \in \mathcal{Z}$ we have

$$\begin{aligned} 0 &\leq \zeta(d(Tx_{m_k}, Tx_{n_k}), C(x_{m_k}, x_{n_k})) \\ &= \zeta(d(x_{m_k-1}, x_{n_k-1}), C(x_{m_k}, x_{n_k})) < 0, \end{aligned}$$

which implies

$$(21) \quad d(x_{m_k-1}, x_{n_k-1}) \leq C(x_{m_k}, x_{n_k})$$

where

$$\begin{aligned} C(x_{m_k}, x_{n_k}) &= [d(x_{m_k}, x_{n_k})]^\beta \cdot [d(x_{m_k}, Tx_{m_k})]^\alpha \\ &\quad \cdot [d(x_{n_k}, Tx_{n_k})]^\gamma \\ &\quad \cdot \left[\frac{1}{2}(d(x_{m_k}, Tx_{n_k}) + d(x_{n_k}, Tx_{m_k})) \right]^{1-\alpha-\beta-\gamma}. \end{aligned}$$

Letting $k \rightarrow \infty$ in the inequality (21), we find that

$$(22) \quad S = \lim_{k \rightarrow \infty} d(x_{m_k-1}, x_{n_k-1}) \leq \lim_{k \rightarrow \infty} C(x_{m_k}, x_{n_k}) = 0,$$

is a contradiction. Thus, we deduce that $S = 0$ and, hence, $\{x_n\}$ is a Cauchy sequence. Since (X, q) is a complete metric space, there exists $u \in X$ such that $\lim_{n \rightarrow \infty} x_n = u$.

We shall show that the point u is a fixed point of T reasoning by contradiction. Suppose that $Tu \neq u$, that is, $d(u, Tu) > 0$. Hence we have

$$\lim_{n \rightarrow \infty} d(Tx_n, Tu) = \lim_{n \rightarrow \infty} d(x_{n+1}, Tu) = d(u, Tu) > 0.$$

Therefore, there is $n_0 \in \mathbb{N}$ such that

$$d(Tx_n, Tu) > 0 \quad \text{for all } n \geq n_0.$$

In particular, $Tx_n \neq Tu$. This also means that $x_n \neq u$ for all $n \geq n_0$. As $d(Tx_n, Tu) > 0$ and $d(x_n, u) > 0$, axiom (ζ_2) and property (6) imply that, for all $n \geq n_0$,

$$0 \leq \zeta(d(Tx_n, Tu), d(x_n, u)) < d(x_n, u) - d(Tx_n, Tu).$$

In particular, $0 \leq d(Tx_n, Tu) \leq d(x_n, u)$ for all $n \geq n_0$, which means that

$$\lim_{n \rightarrow \infty} d(x_{n+1}, Tu) = \lim_{n \rightarrow \infty} d(Tx_n, Tu) = 0.$$

Therefore, $\{x_n\}$ converges, at the same time, to u and to Tu . By the uniqueness of the limit, $u = Tu$, which contradicts $Tu \neq u$. As a consequence, u is a fixed point of T . \square

3. Consequences

In this section, we give some immediate consequence of our main result. The following corollary is the main result of [10].

Corollary 0.1. [10] *Let (X, d) be a complete metric space and $T : X \rightarrow X$ be a mapping such that*

$$d(Tx, Ty) \leq \lambda C(x, y) \quad \text{for all } x, y \in X,$$

where $(C(x, y))$ is defined as in Definition 0.3 and $\lambda \in [0, 1)$. Then T has a unique fixed point in X .

Proof. The result follows from Theorem 0.1 taking into account that T is a \mathcal{Z} -contraction with respect to $\zeta_B \in \mathcal{Z}$, where ζ_B is defined by $\zeta_B(t, s) = \lambda s - t$ for all $s, t \in [0, \infty)$. (see Example 0.1). \square

Corollary 0.2. *Let (X, d) be a complete metric space and let $T : X \rightarrow X$ be a mapping satisfying the following condition:*

$$d(Tx, Ty) \leq C(x, y) - \varphi(C(x, y)) \quad \text{for all } x, y \in X,$$

where $(C(x, y))$ is defined as in Definition 0.3 and $\varphi : [0, \infty) \rightarrow [0, \infty)$ is a lower semi continuous function and $\varphi^{-1}(0) = \{0\}$. Then T has a unique fixed point in X .

Proof. The result follows from Theorem 0.1 taking into account that T is a \mathcal{Z} -contraction with respect to $\zeta_R \in \mathcal{Z}$, where ζ_R is defined by $\zeta_R(t, s) = s - \varphi(s) - t$ for all $s, t \in [0, \infty)$ (see Example 0.1). \square

Corollary 0.3. *Let (X, d) be a complete metric space and $T : X \rightarrow X$ be a mapping. Suppose that for every $x, y \in X$,*

$$d(Tx, Ty) \leq \eta(C(x, y))$$

for all $x, y \in X$, where $(C(x, y))$ is defined as in Definition 0.3 and $\eta : [0, +\infty) \rightarrow [0, +\infty)$ be an upper semi continuous mapping such that $\eta(t) < t$ for all $t > 0$ and $\eta(0) = 0$. Then T has a unique fixed point.

Proof. The result follows from Theorem 0.1 taking into account that T is a \mathcal{Z} -contraction with respect to $\zeta_{BW} \in \mathcal{Z}$, where ζ_{BW} is defined by $\zeta_{BW}(t, s) = \eta(s) - t$ for all $s, t \in [0, \infty)$ (see Example 0.1). \square

Corollary 0.4. *Let (X, d) be a complete metric space and let $T : X \rightarrow X$ be a mapping satisfying the following condition:*

$$\int_0^{d(Tx, Ty)} \phi(t) dt \leq C(x, y) \quad \text{for all } x, y \in X,$$

where $(C(x, y))$ is defined as in Definition 0.3 and $\phi : [0, \infty) \rightarrow [0, \infty)$ is a function such that $\int_0^\epsilon \phi(t) dt$ exists and $\int_0^\epsilon \phi(t) dt > \epsilon$, for each $\epsilon > 0$. Then T has a unique fixed point in X .

Proof. The result follows from Theorem 0.1 taking into account that T is a \mathcal{Z} -contraction with respect to $\zeta_K \in \mathcal{Z}$, where ζ_K is defined by

$$\zeta_K(t, s) = s - \int_0^t \phi(u) du \quad \text{for all } s, t \in [0, \infty)$$

(see Example 0.1). \square

Conclusion

It is clear that the list of consequences in the above section is not complete. In the section above, we give only the fundamental consequences. On the other hand, regarding Example 0.1, one can deduce more results. Furthermore, by changing the terms in $(C(x, y))$ in Definition 0.3, we get more consequences.

Acknowledgements

The author thanks to so much for Professor Themistocles M. Rassias who encourage me so much and his remarkable comments, suggestion and ideas that helps to improve this paper.

REFERENCES

1. H.H. ALSULAMI, E. KARAPINAR, F. KHOJASTEH, A.F. ROLDÁN-LÓPEZ-DE-HIERRO: *A proposal to the study of contractions in quasi-metric spaces*. Discrete Dynamics in Nature and Society. **2014**, Article ID 269286, 10 pages.
2. A.S. S. ALHARBI, H. H. ALSULAMI, AND E.KARAPINAR: *On the Power of Simulation and Admissible Functions in Metric Fixed Point Theory*. Journal of Function Spaces, **2017** (2017), Article ID 2068163, 7 pages
3. B. ALQAHTANI, A.FULGA, E. KARAPINAR: *Fixed Point Results On Δ -Symmetric Quasi-Metric Space Via Simulation Function With An Application To Ulam Stability*. Mathematics 2018, **6**(10), 208
4. H. ARGOUBI, B. SAMET, C. VETRO: *Nonlinear contractions involving simulation functions in a metric space with a partial order*. J. Nonlinear Sci. Appl. **8** (2015), 1082-1094.
5. H. AYDI, A.FELHI, E. KARAPINAR, F.A. ALOJAIL:*Fixed points on quasi-metric spaces via simulation functions and consequences*. J. Math. Anal.(ilirias) **9**(2018) No:2, Pages 10-24.
6. S. BANACH :*Sur les opérations dans les ensembles abstraits et leur application aux équations intégrales*. Fundamenta Mathematicae. **3** (1922), 133-181.
7. F. E. BROWDER, W. V. PETRYSYN :*The solution by iteration of nonlinear functional equation in Banach spaces*. Bull. Amer. Math. Soc. **72** (1966), 571-576.
8. G.E. HARDY, T.D. ROGERS A GENERALIZATION OF A FIXED POINT THEOREM OF REICH. Can. Math. Bull. **16** (1973), 201–206.
9. E. KARAPINAR, R.P. AGARWAL, H. AYDI:*Interpolative Reich-Rus-Ćirić Type Contractions on Partial Metric Spaces*. Mathematics 2018, **6**, 256. <https://doi.org/10.3390/math6110256>
10. E. KARAPINAR, O.ALQAHTANI, H. AYDI:*On Interpolative Hardy-Rogers Type Contractions*. Symmetry 2019, **11**(1), 8 <https://doi.org/10.3390/sym11010008>
11. E.KARAPINAR, A.ROLDAN, D. OREGAN:*Coincidence point theorems on quasi-metric spaces via simulation functions and applications to G-metric spaces*. J. Fixed Point Theory Appl. <https://doi.org/10.1007/s11784-018-0582-x>
12. E. KARAPINAR, F. KHOJASTEH:*An approach to best proximity points results via simulation functions*. J. Fixed Point Theory Appl. **19**(2017)No:3, 1983–1995.
13. E. KARAPINAR :*Fixed points results via simulation functions*. Filomat. **30**(2016) No: 8, 2343–2350.
14. E. KARAPINAR:*Revisiting the Kannan type contractions via interpolation*. Advances in the Theory of Nonlinear Analysis and its Applications. **2** (2018) No:2, 85–87.
15. M.S. KHAN, M. SWALEH, AND S. SESSA:*Fixed point theorems by altering distances between the points*. Bull. Aust. Math. Soc. **30** (1984) No:1, 1–9.
16. F. KHOJASTEH, S. SHUKLA, S. RADENOVIĆ:*A new approach to the study of fixed point theorems via simulation functions*. Filomat. **29** (2015) No:6, 11891194
17. G. MASTROIANNI, G. MILOVANOVIC:*Interpolation Processes:Basic Theory and Applications*. Springer Monographs in Mathematics, 1st edition, (2018) 446 pages
18. A.F. ROLDÁN-LÓPEZ-DE-HIERRO, E. KARAPINAR, C. ROLDÁN-LÓPEZ-DE-HIERRO, J. MARTÍNEZ-MORENO:*Coincidence point theorems on metric spaces via simulation functions*. J. Comput. Appl. Math. **275** (2015) 345–355.

Erdal Karapınar,
Department Of Medical Research,
China Medical University Hospital,
China Medical University, 40402, Taichung, Taiwan
e-mail: erdalkarapinar@yahoo.com