

## EXISTENCE OF SOLUTIONS FOR HYBRID FRACTIONAL PANTOGRAPH EQUATIONS

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In this paper, we study the existence of the hybrid fractional pantograph equation

$$\begin{cases} D_{0+}^{\alpha} \left[ \frac{x(t)}{f(t, x(t), x(\mu t))} \right] = g(t, x(t), x(\sigma t)), & 0 < t < 1, \\ x(0) = 0, \end{cases}$$

where  $\alpha, \mu, \sigma \in (0, 1)$  and  $D_{0+}^{\alpha}$  denotes the Riemann-Liouville fractional derivative. The results are obtained using the technique of measures of noncompactness in the Banach algebras and a fixed point theorem for the product of two operators verifying a Darbo type condition. Some examples are provided to illustrate our results.

### 1. INTRODUCTION

Fractional differential equations are a very important tool in modelling many phenomena of physics and, therefore, they deserve an independent study of their theories parallel to the well-known theory of differential equations, [10, 12, 15, 17]. On the other hand, a great number of papers about differential and integral equations with a modified argument have appeared in the literature recently. Such equations arise in a wide variety of applications such as the modelling of problems from the natural and social sciences, for example, physics, biology and economics. A special class of these equations is the differential equation with affine modification of the argument which can be delay differential equations or differential equations

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with linear modification of the argument. Results concerning with such kind of equations appear in the papers [5, 6, 7, 8, 11, 14, 16, 18, 20], for example.

One of the very special differential equations with linear modification of the argument is the pantograph equation

$$(1) \quad \begin{cases} y'(t) = ay(t) + by(\lambda t), & 0 \leq t \leq T, \\ y(0) = y_0, \end{cases}$$

where  $0 < \lambda < 1$ . This equation appears in different fields of pure and applied mathematics such as number theory, dynamical systems, probability, quantum mechanics, etc.

Recently, in [2], the authors considered the fractional version of the pantograph equation, namely

$$(2) \quad \begin{cases} D_{0+}^{\alpha} u(t) = g(t, u(t), u(\lambda t)), & t \in J = [0, T], \\ u(0) = u_0, \end{cases}$$

where  $\alpha, \lambda \in (0, 1)$ . The Banach contraction principle was the main tool used in this study.

The following hybrid differential of first order

$$(3) \quad \begin{cases} \frac{d}{dt} \left[ \frac{x(t)}{f(t, x(t))} \right] = g(t, x(t)), & t \in J = [0, T], \\ x(t_0) = x_0 \in \mathbb{R}, \end{cases}$$

was studied by DHAGE and LAKSHMIKANTHAM [9], under the assumptions  $f \in C(J \times \mathbb{R}, \mathbb{R} \setminus \{0\})$  and  $g \in C(J \times \mathbb{R}, \mathbb{R})$ .

In [21], ZHAO et al. discussed the fractional version of Eq.(3), i.e.,

$$(4) \quad \begin{cases} D_{0+}^{\alpha} \left[ \frac{x(t)}{f(t, x(t))} \right] = g(t, x(t)), & t \in J, \quad 0 < \alpha < 1, \\ x(0) = 0, \end{cases}$$

where  $f \in C(J \times \mathbb{R}, \mathbb{R} \setminus \{0\})$  and  $g \in C(J \times \mathbb{R}, \mathbb{R})$ , a fixed point theorem in Banach algebras was the main tool used in this work.

In this paper, we study the following hybrid fractional pantograph equation

$$(5) \quad \begin{cases} D_{0+}^{\alpha} \left[ \frac{x(t)}{f(t, x(t), x(\mu t))} \right] = g(t, x(t), x(\sigma t)), & 0 < t < 1, \\ x(0) = 0, \end{cases}$$

where  $0 < \alpha, \mu, \sigma < 1$ ,  $f \in C([0, 1] \times \mathbb{R} \times \mathbb{R}, \mathbb{R} \setminus \{0\})$  and  $g \in C([0, 1] \times \mathbb{R} \times \mathbb{R}, \mathbb{R})$ . The main tool in our study is a fixed point theorem for the product of two operators satisfying a condition of Darbo with respect to a measure of noncompactness. Moreover, we give some applications and examples where our results may be applied and we also compare these results with others appearing in the literature.

## 2. RIEMANN-LIOUVILLE FRACTIONAL DERIVATIVE AND INTEGRAL

We recall some definitions and results about fractional calculus theory from [13].

**Definition 2.1.** *The fractional Riemann-Liouville derivative of order  $\alpha > 0$  of a continuous function  $h : (0, \infty) \rightarrow \mathbb{R}$  is defined by*

$$D_{0+}^{\alpha} h(x) = \frac{1}{\Gamma(n - \alpha)} \frac{d^n}{dx^n} \int_0^x \frac{h(s)}{(x - s)^{\alpha - n + 1}} ds$$

*provided that the right side is pointwise defined on  $(0, \infty)$ , where  $n = [\alpha] + 1$  and  $[\alpha]$  denotes the integer part of  $\alpha$ .*

**Definition 2.2.** *The Riemann-Liouville fractional integral of order  $\alpha > 0$  of a function  $h : (0, \infty) \rightarrow \mathbb{R}$  is defined by*

$$I_{0+}^{\alpha} h(x) = \frac{1}{\Gamma(\alpha)} \int_0^x \frac{h(s)}{(x - s)^{1 - \alpha}} ds,$$

*provided that the right side is pointwise defined on  $(0, \infty)$ .*

**Lemma 2.3.** *Let  $h \in L^1(0, 1)$  and  $0 < \alpha < 1$ . Then*

(a)  $D_{0+}^{\alpha} I_{0+}^{\alpha} h(x) = h(x)$

(b)  $I_{0+}^{\alpha} D_{0+}^{\alpha} h(x) = h(x) - \frac{I_{0+}^{1-\alpha} h(x)|_{x=0}}{\Gamma(\alpha)} x^{\alpha-1}$  a.e. on  $(0, 1)$ .

**Lemma 2.4.** *Let  $0 < \alpha < 1$  and suppose that  $f \in C([0, 1] \times \mathbb{R} \times \mathbb{R}, \mathbb{R} \setminus \{0\})$  and  $y \in C[0, 1]$ . Then, the unique solution of the fractional hybrid initial value problem with linear modification of the argument*

$$(6) \quad \begin{cases} D_{0+}^{\alpha} \left[ \frac{x(t)}{f(t, x(t), x(\mu x))} \right] = y(t), & 0 < t < 1, \\ x(0) = 0, \end{cases}$$

*is given by*

$$x(t) = \frac{f(t, x(t), x(\mu x))}{\Gamma(\alpha)} \int_0^t \frac{y(s)}{(t - s)^{1 - \alpha}} ds, \quad t \in [0, 1].$$

**Proof.** Let  $x(t)$  be a solution of (6). Applying the operator  $I_{0+}^{\alpha}$  to both sides of (6), taking into account Lemma 2.3, we obtain,

$$I_{0+}^{\alpha} D_{0+}^{\alpha} \left[ \frac{x(t)}{f(t, x(t), x(\mu x))} \right] = I_{0+}^{\alpha} y(t),$$

or

$$\frac{x(t)}{f(t, x(t), x(\mu x))} - \frac{I_{0+}^{1-\alpha} \frac{x(t)}{f(t, x(t), x(\mu x))} \Big|_{t=0}}{\Gamma(\alpha)} t^{\alpha-1} = I_{0+}^{\alpha} y(t).$$

Since  $\frac{x(t)}{f(t, x(t), x(\mu x))} \Big|_{t=0} = \frac{x(0)}{f(0, x(0), x(0))} = \frac{0}{f(0, 0, 0)} = 0$  (because  $f(0, 0, 0) \neq 0$ ), we have

$$x(t) = \frac{f(t, x(t), x(\mu x))}{\Gamma(\alpha)} \int_0^t \frac{y(s)}{(t-s)^{1-\alpha}} ds.$$

Conversely, suppose that  $x(t)$  has the expression

$$x(t) = \frac{f(t, x(t), x(\mu x))}{\Gamma(\alpha)} \int_0^t \frac{y(s)}{(t-s)^{1-\alpha}} ds,$$

or

$$(7) \quad x(t) = f(t, x(t), x(\mu x)) I_{0+}^{\alpha} y(t).$$

Applying  $D_{0+}^{\alpha}$  on both sides of (7) after dividing both sides by  $f(t, x(t), x(\mu x))$ , by the aid of Lemma 2.3, we obtain,

$$D_{0+}^{\alpha} \left[ \frac{x(t)}{f(t, x(t), x(\mu x))} \right] = D_{0+}^{\alpha} I_{0+}^{\alpha} y(t) = y(t), \quad 0 < t < 1.$$

Moreover, putting  $t = 0$  in (7), we have  $x(0) = f(0, x(0), x(0)) \cdot 0 = 0$ . This proves that  $x(t)$  is a solution of (6) which completes the proof.

### 3. MEASURE OF NONCOMPACTNESS

Assume that  $E$  is a real Banach space with the norm  $\|\cdot\|$  and the zero element  $\theta$ . By  $B(x, r)$  we denote the closed ball in  $E$  centered at  $x$  with radius  $r$ . By  $B_r$  we denote the ball  $B(\theta, r)$ . If  $X$  is a nonempty subset  $X$  of  $E$  then  $\overline{X}$  and  $\text{Conv } X$  denote the closure and the convex closure of  $X$ , respectively. By  $\text{diam } X$  we denote the diameter of a bounded set  $X$  and  $\|X\|$  is the norm of  $X$ , i.e.,  $\|X\| = \sup\{\|x\| : x \in X\}$ . Further, by  $\mathfrak{M}_E$  we denote the family of all nonempty and bounded subsets of  $E$  and by  $\mathfrak{N}_E$  its subfamily consisting of all relatively compact subsets.

In this paper, we accept the following definition of measure of noncompactness [3].

**Definition 3.5.** A mapping  $\mu : \mathfrak{M}_E \rightarrow \mathbb{R}_+ = [0, \infty)$  will be called a measure of noncompactness in  $E$  if it satisfies the following conditions:

- 1° The family  $\ker \mu = \{X \in \mathfrak{M}_E : \mu(X) = 0\}$  is nonempty and  $\ker \mu \subset \mathfrak{N}_E$ .
- 2°  $X \subset Y \Rightarrow \mu(X) \leq \mu(Y)$ .
- 3°  $\mu(\overline{X}) = \mu(X)$ .
- 4°  $\mu(\text{Conv } X) = \mu(X)$ .
- 5°  $\mu(\mu X + (1 - \mu)Y) \leq \mu \mu(X) + (1 - \mu) \mu(Y)$  for  $\mu \in [0, 1]$ .

6° If  $(X_n)$  is a sequence of closed subsets of  $\mathfrak{M}_E$  such that  $X_{n+1} \subset X_n$  and  $\lim_{n \rightarrow \infty} \mu(X_n) = 0$  then  $X_\infty = \bigcap_{n=1}^{\infty} X_n \neq \phi$ .

The family  $\ker \mu$  appearing in 1° is called the kernel of the measure of noncompactness  $\mu$ . Notice that the set  $X_\infty$  appearing in 6° belongs to  $\ker \mu$ . Indeed, since  $\mu(X_\infty) \leq \mu(X_n)$  for any  $n = 1, 2, \dots$ , we infer that  $\mu(X_\infty) = 0$  which means that  $X_\infty \in \ker \mu$ .

In the sequel, we assume that the space  $E$  has structure of Banach algebra. We denote by  $xy$  the products of two elements  $x, y \in E$  and by  $XY$  the set defined by  $XY = \{xy : x \in X, y \in Y\}$ .

Now, we recall the following concept which will play an important role in our considerations (see [4]).

**Definition 3.6.** Let  $E$  be a Banach algebra. We say that a measure of noncompactness  $\mu$  defined on  $E$  satisfies condition (m) if the following is satisfied

$$\mu(XY) \leq \|X\|\mu(Y) + \|Y\|\mu(X), \text{ for any } X, Y \in \mathfrak{M}_E.$$

AGHAJANI et al. [1] proved the following generalization of fixed point theorem due to Darbo.

**Theorem 3.7** (Theorem 2.2 of [1]). Let  $\Omega$  be a nonempty, bounded, closed and convex subset of a Banach space  $E$  and let  $T : \Omega \rightarrow \Omega$  be a continuous operator satisfying

$$(8) \quad \mu(TX) \leq \varphi(\mu(X)),$$

for any nonempty subset  $X$  of  $\Omega$ , where  $\mu$  is an arbitrary measure of noncompactness and  $\varphi : \mathbb{R}_+ \rightarrow \mathbb{R}_+$  is a nondecreasing function such that  $\lim_{n \rightarrow \infty} \varphi^n(t) = 0$  for each  $t \in \mathbb{R}_+$ , where  $\varphi^n$  denotes the  $n$ -iteration of  $\varphi$ .

Then  $T$  has at least one fixed point in  $\Omega$ .

Also, the authors of [1] proved the following lemma which will be useful in our considerations.

**Lemma 3.8** (Lemma 2.1 of [1]). Let  $\varphi : \mathbb{R}_+ \rightarrow \mathbb{R}_+$  be a nondecreasing and upper semicontinuous function. Then, the following conditions are equivalent:

- (i)  $\lim_{n \rightarrow \infty} \varphi^n(t) = 0$ , for any  $t \geq 0$
- (ii)  $\varphi(t) < t$ , for any  $t > 0$ .

For convenience, we denote by  $\mathcal{A}$  the class of functions given by

$$\mathcal{A} = \{\varphi : \mathbb{R}_+ \rightarrow \mathbb{R}_+ : \varphi \text{ is nondecreasing and } \lim_{n \rightarrow \infty} \varphi^n(t) = 0 \text{ for any } t > 0\},$$

where  $\varphi^n$  denotes the  $n$ -iteration of  $\varphi$ .

REMARK 3.9. It is easy to see that if  $\varphi \in \mathcal{A}$  then  $\varphi(t) < t$ , for any  $t > 0$ . Indeed, in contrary case, we can find  $t_0 > 0$  and  $t_0 \leq \varphi(t_0)$ . By using the nondecreasing character of  $\varphi$ , we have

$$0 < t_0 \leq \varphi(t_0) \leq \varphi^2(t_0) \leq \dots \leq \varphi^n(t_0) \leq \dots,$$

and, consequently,  $0 < t_0 \leq \lim_{n \rightarrow \infty} \varphi^n(t_0)$  which contradicts the fact that  $\varphi \in \mathcal{A}$ . Moreover, this proves that if  $\varphi \in \mathcal{A}$  then  $\varphi$  is continuous at  $t_0 = 0$ .

REMARK 3.10. By using Remark 3.9, the contractive condition appearing in Theorem 3.7 can be rewritten as  $\mu(TX) < \mu(X)$  for any  $X \in \mathfrak{M}_E \setminus \ker \mu$  and, therefore, Theorem 3.7 is a immediate consequence of Sadovskii theorem [19].

In this paper, we work in the space  $C[0, 1]$  consisting of all real functions defined and continuous on the interval  $[0, 1]$  with the usual supremum norm

$$\|x\| = \sup\{|x(t)| : t \in [0, 1]\},$$

for  $x \in C[0, 1]$ . Notice that the space  $C[0, 1]$  is a Banach algebra, where the multiplication is defined as the usual product of real functions.

Next, we present the measure of noncompactness in  $C[0, 1]$  which will be used in our study. Let us fix a set  $X \in \mathfrak{M}_{C[0,1]}$  and  $\varepsilon > 0$ . For  $x \in X$ , we denote by  $\omega(x, \varepsilon)$  the modulus of continuity of  $x$ , i.e.,

$$\omega(x, \varepsilon) = \sup\{|x(t) - x(s)| : t, s \in [0, 1], |t - s| \leq \varepsilon\}.$$

Further, put

$$\omega(X, \varepsilon) = \sup\{\omega(x, \varepsilon) : x \in X\}$$

and

$$\omega_0(X) = \lim_{\varepsilon \rightarrow 0} \omega(X, \varepsilon).$$

In [3], it is proved that  $\omega_0(X)$  is a measure of noncompactness in  $C[0, 1]$ .

**Proposition 3.11.** *The measure of noncompactness  $\omega_0$  on  $C[0, 1]$  satisfies condition (m).*

**Proof.** Fix  $X, Y \in \mathfrak{M}_{C[0,1]}$ ,  $\varepsilon > 0$  and  $t, s \in [0, 1]$  with  $|t - s| \leq \varepsilon$ . Then, for  $x \in X$  and  $y \in Y$ , we have,

$$\begin{aligned} |x(t)y(t) - x(s)y(s)| &\leq |x(t)y(t) - x(t)y(s)| + |x(t)y(s) - x(s)y(s)| \\ &= |x(t)| |y(t) - y(s)| + |y(s)| |x(t) - x(s)| \\ &\leq \|x\| \omega(y, \varepsilon) + \|y\| \omega(x, \varepsilon). \end{aligned}$$

This gives us,

$$\omega(xy, \varepsilon) \leq \|x\| \omega(y, \varepsilon) + \|y\| \omega(x, \varepsilon),$$

and, consequently,

$$\omega(XY, \varepsilon) \leq \|X\| \omega(Y, \varepsilon) + \|Y\| \omega(X, \varepsilon).$$

Taking  $\varepsilon \rightarrow 0$ , we get,

$$\omega_0(XY) \leq \|X\| \omega_0(Y) + \|Y\| \omega_0(X).$$

#### 4. MAIN RESULTS

Here, we study (5) under the following assumptions:

(a<sub>1</sub>)  $f \in C([0, 1] \times \mathbb{R} \times \mathbb{R}, \mathbb{R} \setminus \{0\})$  and  $g \in C([0, 1] \times \mathbb{R} \times \mathbb{R}, \mathbb{R})$ .

(a<sub>2</sub>) The functions  $f$  and  $g$  satisfy

$$|f(t, x_1, x_2) - f(t, \hat{x}_1, \hat{x}_2)| \leq \varphi_1(\max(|x_1 - \hat{x}_1|, |x_2 - \hat{x}_2|))$$

and

$$|g(t, x_1, x_2) - g(t, \hat{x}_1, \hat{x}_2)| \leq \varphi_2(\max(|x_1 - \hat{x}_1|, |x_2 - \hat{x}_2|)),$$

respectively, for any  $t \in [0, 1]$  and  $x_1, \hat{x}_1, x_2, \hat{x}_2 \in \mathbb{R}$ , where  $\varphi_1, \varphi_2 \in \mathcal{A}$  and  $\varphi_1$  is continuous.

Notice that assumption (a<sub>1</sub>) gives us the existence of two nonnegative constants  $k_1$  and  $k_2$  such that  $|f(t, 0, 0)| \leq k_1$  and  $|g(t, 0, 0)| \leq k_2$  for any  $t \in [0, 1]$ .

(a<sub>3</sub>) There exists  $r_0 > 0$  satisfying the inequalities

$$(\varphi_1(r) + k_1) \cdot (\varphi_2(r) + k_2) \leq r\Gamma(\alpha + 1)$$

and

$$\varphi_2(r) + k_2 \leq \Gamma(\alpha + 1).$$

For further purposes, by Lemma 2.4 we have that any solution of (5) must satisfy the integral equation

$$x(t) = \frac{f(t, x(t), x(\mu t))}{\Gamma(\alpha)} \int_0^t \frac{g(s, x(s), x(\sigma s))}{(t-s)^{1-\alpha}} ds, \quad 0 \leq t \leq 1.$$

Therefore, the fixed points of the operator  $\mathcal{T}$  defined on  $C[0, 1]$  by

$$(9) \quad (\mathcal{T}x)(t) = \frac{f(t, x(t), x(\mu t))}{\Gamma(\alpha)} \int_0^t \frac{g(s, x(s), x(\sigma s))}{(t-s)^{1-\alpha}} ds, \quad 0 \leq t \leq 1,$$

are the solutions of Eq.(5).

**Theorem 4.12.** *Under assumptions (a<sub>1</sub>) – (a<sub>3</sub>), (5) has at least one solution in  $C[0, 1]$ .*

**Proof.** Consider the operators  $\mathcal{F}$  and  $\mathcal{G}$  defined on  $C[0, 1]$  by

$$(\mathcal{F}x)(t) = f(t, x(t), x(\mu t))$$

and

$$(\mathcal{G}x)(t) = \frac{1}{\Gamma(\alpha)} \int_0^t \frac{g(s, x(s), x(\sigma s))}{(t-s)^{1-\alpha}} ds$$

for any  $x \in C[0, 1]$  and  $t \in [0, 1]$ . Therefore,  $\mathcal{T}x = (\mathcal{F}x) \cdot (\mathcal{G}x)$ , for any  $x \in C[0, 1]$ .

For better readability, we divide the proof in several steps.

**Step 1.**  $\mathcal{T} : C[0, 1] \rightarrow C[0, 1]$ .

In fact, we prove that  $\mathcal{F}x, \mathcal{G}x \in C[0, 1]$  for  $x \in C[0, 1]$  and, since the product of continuous functions is a continuous function, our claim will be proved.

First, we prove that if  $x \in C[0, 1]$  then  $\mathcal{F}x \in C[0, 1]$ . By assumption  $(a_1)$  and, since that  $x \in C[0, 1]$  then  $x \circ \lambda \in C[0, 1]$ , where  $\lambda : [0, 1] \rightarrow [0, 1]$  is given by  $\lambda(t) = \mu t$ , we infer that  $\mathcal{F}x \in C[0, 1]$ . Now, we prove that if  $x \in C[0, 1]$  then  $\mathcal{G}x \in C[0, 1]$ . We fix  $t_0 \in [0, 1]$  and let  $(t_n)$  be a sequence in  $[0, 1]$  such that  $t_n \rightarrow t_0$ . We have to prove that  $(\mathcal{G}x)(t_n) \rightarrow (\mathcal{G}x)(t_0)$ . In fact, without loss of generality we can suppose that  $t_n > t_0$ . Then, we have

$$\begin{aligned} |(\mathcal{G}x)(t_n) - (\mathcal{G}x)(t_0)| &= \frac{1}{\Gamma(\alpha)} \left| \int_0^{t_n} \frac{g(s, x(s), x(\sigma s))}{(t_n - s)^{1-\alpha}} ds - \int_0^{t_0} \frac{g(s, x(s), x(\sigma s))}{(t_0 - s)^{1-\alpha}} ds \right| \\ &\leq \frac{1}{\Gamma(\alpha)} \left| \int_0^{t_n} \frac{g(s, x(s), x(\sigma s))}{(t_n - s)^{1-\alpha}} ds - \int_0^{t_n} \frac{g(s, x(s), x(\sigma s))}{(t_0 - s)^{1-\alpha}} ds \right| \\ &\quad + \frac{1}{\Gamma(\alpha)} \left| \int_0^{t_n} \frac{g(s, x(s), x(\sigma s))}{(t_0 - s)^{1-\alpha}} ds - \int_0^{t_0} \frac{g(s, x(s), x(\sigma s))}{(t_0 - s)^{1-\alpha}} ds \right| \\ &\leq \frac{1}{\Gamma(\alpha)} \int_0^{t_n} |(t_n - s)^{\alpha-1} - (t_0 - s)^{\alpha-1}| |g(s, x(s), x(\sigma s))| ds \\ &\quad + \frac{1}{\Gamma(\alpha)} \int_{t_0}^{t_n} |(t_0 - s)^{\alpha-1}| |g(s, x(s), x(\sigma s))| ds. \end{aligned}$$

Since  $g \in C([0, 1] \times \mathbb{R} \times \mathbb{R}, \mathbb{R})$ ,  $g$  is bounded on  $[0, 1] \times [-\|x\|, \|x\|] \times [-\|x\|, \|x\|]$ . Put  $M = \sup\{|g(s, y_1, y_2)| : s \in [0, 1], y_1, y_2 \in [-\|x\|, \|x\|]\}$ . From the last estimate, we get

$$\begin{aligned} |(\mathcal{G}x)(t_n) - (\mathcal{G}x)(t_0)| &\leq \frac{M}{\Gamma(\alpha)} \int_0^{t_n} |(t_n - s)^{\alpha-1} - (t_0 - s)^{\alpha-1}| ds \\ &\quad + \frac{M}{\Gamma(\alpha)} \int_{t_0}^{t_n} |(t_0 - s)^{\alpha-1}| ds. \end{aligned}$$

Since  $0 < \alpha < 1$  and  $t_n > t_0$ , we have,

$$\begin{aligned} |(\mathcal{G}x)(t_n) - (\mathcal{G}x)(t_0)| &\leq \frac{M}{\Gamma(\alpha)} \left[ \int_0^{t_0} |(t_n - s)^{\alpha-1} - (t_0 - s)^{\alpha-1}| ds \right. \\ &\quad \left. + \int_{t_0}^{t_n} |(t_n - s)^{\alpha-1} - (t_0 - s)^{\alpha-1}| ds \right] + \frac{M}{\Gamma(\alpha)} \int_{t_0}^{t_n} \frac{1}{(s - t_0)^{1-\alpha}} ds \\ &= \frac{M}{\Gamma(\alpha)} \left[ \int_0^{t_0} [(t_0 - s)^{\alpha-1} - (t_n - s)^{\alpha-1}] ds \right. \\ &\quad \left. + \int_{t_0}^{t_n} \frac{ds}{(t_n - s)^{1-\alpha}} + \int_{t_0}^{t_n} \frac{ds}{(s - t_0)^{1-\alpha}} \right] + \frac{M}{\Gamma(\alpha)} \int_{t_0}^{t_n} \frac{1}{(s - t_0)^{1-\alpha}} ds \end{aligned}$$



$$\begin{aligned} &\leq \frac{M}{\Gamma(\alpha+1)} [(t_n - t_0)^\alpha + t_0^\alpha - t_n^\alpha + (t_n - t_0)^\alpha + (t_n - t_0)^\alpha] + \frac{M}{\Gamma(\alpha+1)} (t_n - t_0)^\alpha \\ &\leq \frac{4M}{\Gamma(\alpha+1)} (t_n - t_0)^\alpha + \frac{M}{\Gamma(\alpha+1)} (t_0^\alpha - t_n^\alpha) < \frac{4M}{\Gamma(\alpha+1)} (t_n - t_0)^\alpha, \end{aligned}$$

where we have used the fact that  $t_0^\alpha - t_n^\alpha < 0$  in the last inequality. Since  $t_n \rightarrow t_0$ , the last estimate gives us that  $(\mathcal{G}x)(t_n) \rightarrow (\mathcal{G}x)(t_0)$ . Therefore,  $\mathcal{G}x \in C[0, 1]$ . This proves that if  $x \in C[0, 1]$  then  $\mathcal{T}x \in C[0, 1]$ .

**Step 2.** An estimate of  $\|\mathcal{T}x\|$  for  $x \in C[0, 1]$ .

Fix  $x \in C[0, 1]$  and  $t \in [0, 1]$ . Then, taking into account our assumptions, we get,

$$\begin{aligned} |(\mathcal{T}x)(t)| &= |(\mathcal{F}x)(t)| |(\mathcal{G}x)(t)| \\ &= |f(t, x(t), x(\mu t))| \left| \frac{1}{\Gamma(\alpha)} \int_0^t \frac{g(s, x(s), x(\sigma s))}{(t-s)^{1-\alpha}} ds \right| \\ &\leq [ |f(t, x(t), x(\mu t)) - f(t, 0, 0)| + |f(t, 0, 0)| ] \\ &\quad \times \left[ \frac{1}{\Gamma(\alpha)} \left| \int_0^t \frac{g(s, x(s), x(\sigma s)) - g(s, 0, 0)}{(t-s)^{1-\alpha}} ds + \int_0^t \frac{g(s, 0, 0)}{(t-s)^{1-\alpha}} ds \right| \right] \\ &\leq \frac{1}{\Gamma(\alpha)} [\varphi_1(\max(|x(t)|, |x(\mu t)|)) + k_1] \left[ \int_0^t \frac{|g(s, x(s), x(\sigma s)) - g(s, 0, 0)|}{(t-s)^{1-\alpha}} ds \right. \\ &\quad \left. + \int_0^t \frac{|g(s, 0, 0)|}{(t-s)^{1-\alpha}} ds \right] \\ &\leq \frac{1}{\Gamma(\alpha)} [\varphi_1(\max(\|x\|, \|x\|)) + k_1] \left[ \int_0^t \frac{\varphi_2(\max(|x(s)|, |x(\sigma s)|))}{(t-s)^{1-\alpha}} ds \right. \\ &\quad \left. + k_2 \int_0^t \frac{ds}{(t-s)^{1-\alpha}} \right] \\ &\leq \frac{1}{\Gamma(\alpha)} [\varphi_1(\max(\|x\|, \|x\|)) + k_1] \cdot [\varphi_2(\max(\|x\|, \|x\|)) + k_2] \int_0^t \frac{ds}{(t-s)^{1-\alpha}} \\ &\leq \frac{1}{\Gamma(\alpha+1)} (\varphi_1(\|x\|) + k_1) \cdot (\varphi_2(\|x\|) + k_2). \end{aligned}$$

Consequently,

$$\|\mathcal{T}x\| \leq \frac{1}{\Gamma(\alpha+1)} [\varphi_1(\|x\|) + k_1] \cdot [\varphi_2(\|x\|) + k_2].$$

From assumption  $(a_3)$ , it follows that the operator  $\mathcal{T}$  transforms  $B_{r_0}$  into itself. Moreover, from the last estimates, we get

$$(10) \quad \|\mathcal{F}B_{r_0}\| \leq \varphi_1(r_0) + k_1$$

and

$$(11) \quad \|\mathcal{G}B_{r_0}\| \leq \frac{\varphi_2(r_0) + k_2}{\Gamma(\alpha + 1)}.$$

**Step 3.** The operators  $\mathcal{F}$  and  $\mathcal{G}$  are continuous on the ball  $B_{r_0}$ .

First, we prove that  $\mathcal{F}$  is continuous on  $B_{r_0}$ . To do this, we fix  $\varepsilon > 0$  and we take  $x, y \in B_{r_0}$  with  $\|x - y\| \leq \varepsilon$ . Then, for  $t \in [0, 1]$ , we have,

$$\begin{aligned} |(\mathcal{F}x)(t) - (\mathcal{F}y)(t)| &= |f(t, x(t), x(\mu t)) - f(t, y(t), x(\mu t))| \\ &\leq \varphi_1(\max(|x(t) - y(t)|, |x(\mu t), y(\mu t)|)) \\ &\leq \varphi_1(\max(\|x - y\|, \|x - y\|)) \leq \varphi_1(\|x - y\|) \leq \varphi_1(\varepsilon) < \varepsilon. \end{aligned}$$

The last estimate proves that  $\mathcal{F}$  is continuous on  $B_{r_0}$ , where we have used Remark 3.9.

Next, we prove that  $\mathcal{G}$  is continuous on  $B_{r_0}$ . In order to do this, we fix  $\varepsilon > 0$  and take  $x, y \in B_{r_0}$  with  $\|x - y\| \leq \varepsilon$ . Then, for  $t \in [0, 1]$ , we have,

$$\begin{aligned} |(\mathcal{G}x)(t) - (\mathcal{G}y)(t)| &= \frac{1}{\Gamma(\alpha)} \left| \int_0^t \frac{g(s, x(s), x(\sigma s))}{(t-s)^{1-\alpha}} ds - \int_0^t \frac{g(s, y(s), y(\sigma s))}{(t-s)^{1-\alpha}} ds \right| \\ &\leq \frac{1}{\Gamma(\alpha)} \int_0^t \frac{|g(s, x(s), x(\sigma s)) - g(s, y(s), y(\sigma s))|}{(t-s)^{1-\alpha}} ds \\ &\leq \frac{1}{\Gamma(\alpha)} \int_0^t \frac{\varphi_2(\max(|x(s) - y(s)|, |x(\sigma s) - y(\sigma s)|))}{(t-s)^{1-\alpha}} ds \\ &\leq \frac{1}{\Gamma(\alpha)} \varphi_2(\max(\|x - y\|, \|x - y\|)) \int_0^t \frac{ds}{(t-s)^{1-\alpha}} \\ &\leq \frac{1}{\Gamma(\alpha + 1)} \varphi_2(\|x - y\|) t^\alpha \leq \frac{1}{\Gamma(\alpha + 1)} \varphi_2(\varepsilon) < \frac{\varepsilon}{\Gamma(\alpha + 1)}, \end{aligned}$$

where we have used the fact that  $\varphi_2(\varepsilon) < \varepsilon$  (Remark 3.9). The last chain of inequalities gives us

$$\|\mathcal{G}x - \mathcal{G}y\| < \frac{\varepsilon}{\Gamma(\alpha + 1)}$$

and this proves the continuity of the operator  $\mathcal{G}$  on  $B_{r_0}$ . Finally, since  $\mathcal{T} = \mathcal{F} \cdot \mathcal{G}$ , it follows that  $\mathcal{T}$  is continuous on  $B_{r_0}$ .

**Step 4.** For  $\phi \neq X \subset B_{r_0}$ , estimates of  $\omega_0(\mathcal{F}X)$  and  $\omega_0(\mathcal{G}X)$ .

Fix  $\varepsilon > 0$  and take  $x \in X$  and  $t_1, t_2 \in [0, 1]$  with  $|t_1 - t_2| \leq \varepsilon$ . Then,

$$\begin{aligned} |(\mathcal{F}x)(t_1) - (\mathcal{F}x)(t_2)| &= |f(t_1, x(t_1), x(\mu t_1)) - f(t_2, x(t_2), x(\mu t_2))| \\ &\leq |f(t_1, x(t_1), x(\mu t_1)) - f(t_1, x(t_2), x(\mu t_2))| \end{aligned}$$

$$\begin{aligned}
& + |f(t_1, x(t_2), x(\mu t_2)) - f(t_2, x(t_2), x(\mu t_2))| \\
& \leq \varphi_1 (\max(|x(t_1) - x(t_2)|, |x(\mu t_1) - x(\mu t_2)|)) + \omega(f, \varepsilon) \\
& \leq \varphi_1 (\max(\omega(x, \varepsilon), \omega(x, \mu\varepsilon))) + \omega(f, \varepsilon),
\end{aligned}$$

where  $\omega(f, \varepsilon)$  denotes the quantity

$$\omega(f, \varepsilon) = \sup\{|f(t_1, x, y) - f(t_2, x, y)| : t_1, t_2 \in [0, 1], |t_1 - t_2| \leq \varepsilon, x, y \in [-r_0, r_0]\}.$$

Therefore,

$$\omega(\mathcal{F}X, \varepsilon) \leq \varphi_1 (\max(\omega(X, \varepsilon), \omega(X, \mu\varepsilon))) + \omega(f, \varepsilon),$$

and, since  $f(t, x, y)$  is uniformly continuous on bounded subsets of  $[0, 1] \times \mathbb{R} \times \mathbb{R}$ ,  $\omega(f, \varepsilon) \rightarrow 0$  as  $\varepsilon \rightarrow 0$ . From the last inequality and using the fact that  $\varphi_1$  is continuous, we infer

$$\begin{aligned}
(12) \quad \omega_0(\mathcal{F}X) & \leq \varphi_1 (\max(\lim_{\varepsilon \rightarrow 0} \omega(X, \varepsilon), \lim_{\varepsilon \rightarrow 0} \omega(X, \mu\varepsilon))) \\
& = \varphi_1 (\max(\omega_0(X), \omega_0(X))) = \varphi_1(\omega_0(X)).
\end{aligned}$$

Now, we estimate  $\omega_0(\mathcal{G}X)$ . Fix  $\varepsilon > 0$  and we take  $x \in X$ ,  $t_1, t_2 \in [0, 1]$  with  $|t_1 - t_2| \leq \varepsilon$ . Without loss of generality, we can suppose that  $t_1 < t_2$ , then

$$\begin{aligned}
|(\mathcal{G}x)(t_1) - (\mathcal{G}x)(t_2)| & = \frac{1}{\Gamma(\alpha)} \left| \int_0^{t_2} \frac{g(s, x(s), x(\sigma s))}{(t_2 - s)^{1-\alpha}} ds - \int_0^{t_1} \frac{g(s, x(s), x(\sigma s))}{(t_1 - s)^{1-\alpha}} ds \right| \\
& \leq \frac{1}{\Gamma(\alpha)} \left[ \int_0^{t_1} |(t_2 - s)^{\alpha-1} - (t_1 - s)^{\alpha-1}| |g(s, x(s), x(\sigma s))| ds \right. \\
& \quad \left. + \int_{t_1}^{t_2} (t_2 - s)^{\alpha-1} |g(s, x(s), x(\sigma s))| ds \right] \\
& \leq \frac{1}{\Gamma(\alpha)} \left[ \int_0^{t_1} [(t_1 - s)^{\alpha-1} - (t_2 - s)^{\alpha-1}] |g(s, x(s), x(\sigma s))| ds \right. \\
& \quad \left. + \int_{t_1}^{t_2} (t_2 - s)^{\alpha-1} |g(s, x(s), x(\sigma s))| ds \right]
\end{aligned}$$

Since  $g(t, x)$  is continuous on  $[0, 1] \times \mathbb{R} \times \mathbb{R}$ , it is bounded on the compact set  $[0, 1] \times [-r_0, r_0] \times [-r_0, r_0]$ . Put  $L = \sup\{|g(t, x, y)| : t \in [0, 1], x, y \in [-r_0, r_0]\}$ . Then, from the last inequality, it follows that,

$$\begin{aligned}
& |(\mathcal{G}x)(t_1) - (\mathcal{G}x)(t_2)| \\
& \leq \frac{L}{\Gamma(\alpha)} \left[ \int_0^{t_1} [(t_1 - s)^{\alpha-1} - (t_2 - s)^{\alpha-1}] ds + \int_{t_1}^{t_2} (t_2 - s)^{\alpha-1} ds \right] \\
& \leq \frac{L}{\Gamma(\alpha + 1)} [(t_2 - t_1)^\alpha + t_1^\alpha - t_2^\alpha + (t_2 - t_1)^\alpha] \\
& \leq \frac{2L}{\Gamma(\alpha + 1)} (t_2 - t_1)^\alpha \leq \frac{2L}{\Gamma(\alpha + 1)} \varepsilon^\alpha,
\end{aligned}$$

where we have used the fact that  $t_1^\alpha - t_2^\alpha \leq 0$ . Therefore,

$$\omega(\mathcal{G}x, \varepsilon) \leq \frac{2L}{\Gamma(\alpha + 1)} \varepsilon^\alpha,$$

and this gives us

$$(13) \quad \omega(\mathcal{G}X, \varepsilon) \leq \frac{2L}{\Gamma(\alpha + 1)} \varepsilon^\alpha.$$

Taking  $\varepsilon \rightarrow 0$ , we get  $\omega_0(\mathcal{G}X) = 0$ .

**Step 5.** For  $\phi \neq X \subset B_{r_0}$ , an estimate of  $\omega_0(\mathcal{T}X)$ .

Taking into account Proposition 3.11, (9), (12) and (13), we have

$$\begin{aligned} \omega_0(\mathcal{T}X) &= \omega_0(\mathcal{F}X \cdot \mathcal{G}X) \leq \|\mathcal{F}X\| \omega_0(\mathcal{G}X) + \|\mathcal{G}X\| \omega_0(\mathcal{F}X) \\ &\leq \|\mathcal{F}B_{r_0}\| \omega_0(\mathcal{G}X) + \|\mathcal{G}B_{r_0}\| \omega_0(\mathcal{F}X) \\ &\leq \frac{1}{\Gamma(\alpha + 1)} (\varphi_2(r_0) + k_2) \cdot \varphi_1(\omega_0(X)). \end{aligned}$$

By assumption  $(a_3)$ ,  $\varphi_2(r_0) + k_2 \leq \Gamma(\alpha + 1)$ , and, therefore,

$$\frac{1}{\Gamma(\alpha + 1)} (\varphi_2(r_0) + k_2) \cdot \varphi_1 \in \mathcal{A}$$

(it is easy to prove that if  $\beta \in [0, 1]$  and  $\varphi \in \mathcal{A}$  then  $\beta\varphi \in \mathcal{A}$ ).

Finally, by Theorem 3.7, the operator  $\mathcal{T}$  has at least one fixed point in  $B_{r_0}$ . This completes the proof.

## 5. APPLICATIONS AND EXAMPLES

The nonoscillatory character of the problems the solutions of (5) is an interesting question in real world. It means that the solutions of (5) have a constant sign. In connection with this question, we notice that if  $f(t, x, y)$  and  $g(t, x, y)$  have the same constant sign (this means that  $f(t, x, y) > 0$  and  $g(t, x, y) \geq 0$  or  $f(t, x, y) < 0$  and  $g(t, x, y) \leq 0$  for any  $t \in [0, 1]$  and  $x, y \in \mathbb{R}$ ) and under assumptions of Theorem 4.12 then the solution  $x(t)$  of (5) is nonnegative. This is due to the fact that the solutions of (5) satisfy the integral equation

$$(14) \quad x(t) = \frac{f(t, x(t), x(\mu t))}{\Gamma(\alpha)} \int_0^t \frac{g(s, x(s), x(\sigma s))}{(t-s)^{1-\alpha}} ds, \quad 0 \leq t \leq 1.$$

Moreover, the following proposition connects with the above mentioned question.

**Proposition 5.13.** *Under assumptions of Theorem 4.12 and suppose that  $g(t, x, y)$  has constant sign and  $g(t, x, y) \neq 0$  for  $t \in [0, 1]$  and  $x, y \in \mathbb{R}$  then the solution  $x(t)$  of (5) obtained by Theorem 4.12 verifies that  $x(t) \neq 0$  for  $0 < t < 1$ .*

**Proof.** Assume the contrary, we can find  $t^* \in (0, 1)$  with  $x(t^*) = 0$ . Next, since  $x(t)$  satisfies Eq.(14), we have,

$$0 = x(t^*) = \frac{f(t^*, 0, x(\mu t^*))}{\Gamma(\alpha)} \int_0^{t^*} \frac{g(s, x(s), x(\sigma s))}{(t^* - s)^{1-\alpha}} ds.$$

Taking into account that  $f(t, x, y) \neq 0$  for any  $t \in [0, 1]$  and  $x, y \in \mathbb{R}$ , we infer that

$$(15) \quad \int_0^{t^*} (t^* - s)^{\alpha-1} g(s, x(s), x(\sigma s)) ds = 0.$$

Since  $g(t, x, y)$  has constant sign and  $(t^* - s)^{\alpha-1} > 0$  for  $s \in [0, t^*]$ , we deduce that

$$g(s, x(s), x(\sigma s)) = 0 \text{ a.e. } s \in [0, t^*].$$

This contradicts the fact that  $g(t, x, y) \neq 0$  for  $(t, x, y) \in [0, 1] \times \mathbb{R} \times \mathbb{R}$  which completes the proof.  $\square$

The following corollary is an application of Bolzano's theorem.

**Corollary 5.14.** *Under assumptions of Proposition 5.13, the solution  $x(t)$  of (5) obtained by Theorem 4.12 satisfies that  $x(t) > 0$  for  $t \in (0, 1)$  or  $x(t) < 0$  for  $t \in (0, 1)$ .*

On the other hand, if we perturb the data function in (5)

$$(16) \quad \begin{cases} D_{0+}^{\alpha} \left[ \frac{x(t)}{f(t, x(t), x(\mu t))} \right] = g(t, x(t), x(\sigma t)) + \eta(t), & 0 < t < 1, \\ x(0) = 0, \end{cases}$$

where  $0 < \alpha, \mu, \sigma < 1$ ,  $f \in C([0, 1] \times \mathbb{R} \times \mathbb{R}, \mathbb{R} \setminus \{0\})$ ,  $g \in C([0, 1] \times \mathbb{R} \times \mathbb{R}, \mathbb{R})$  and  $\eta \in C[0, 1]$ , the assumptions  $(a_1)$  and  $(a_2)$  of Theorem 4.12 are satisfied if  $f(t, x, y)$  and  $g(t, x, y)$  also satisfy them and only, we would have to check assumption  $(a_3)$ . This fact makes that our theorem (Theorem 4.12) is very applicable.

Next, we present an example illustrating Theorem 4.12.

**EXAMPLE 5.15.** Consider the following fractional hybrid problem

$$(17) \quad \begin{cases} D_{0+}^{\frac{1}{2}} \left[ \frac{x(t)}{\left[ \frac{t}{4} + \ln(1 + |x(\frac{t}{3})|) + \frac{1}{4} \right]} \right] = \frac{1}{4} + \frac{1}{10}x(t) + \frac{1}{10}x\left(\frac{t}{2}\right), & 0 < t < 1, \\ x(0) = 0. \end{cases}$$

Notice that this problem is a particular case of (5), where  $\alpha = \frac{1}{2}$ ,  $\mu = \frac{1}{3}$ ,  $\sigma = \frac{1}{2}$ ,  $f(t, x, y) = \frac{t}{4} + \ln(1 + |y|) + \frac{1}{4}$  and  $g(t, x, y) = \frac{1}{4} + \frac{x}{10} + \frac{y}{10}$ .

It is clear that the functions  $f$  and  $g$  satisfy  $(a_1)$  of Theorem 4.12 with  $|f(t, 0, 0)| = \left| \frac{t}{4} + \frac{1}{4} \right|$  and  $|g(t, 0, 0)| = \frac{1}{4}$ . Therefore,  $k_1 = \frac{1}{2}$  and  $k_1 = \frac{1}{4}$ . Moreover, for any  $x_1, x_2, \hat{x}_1, \hat{x}_2 \in \mathbb{R}$  and any  $t \in [0, 1]$ , we have

$$|f(t, x_1, x_2) - f(t, \hat{x}_1, \hat{x}_2)| = |\ln(1 + |x_2|) - \ln(1 + |\hat{x}_2|)|$$

$$\begin{aligned} &= \ln \left( \frac{1 + |x_2|}{1 + |\widehat{x}_2|} \right) = \ln \left( 1 + \frac{|x_2| - |\widehat{x}_2|}{1 + |\widehat{x}_2|} \right) \\ &\leq \ln(1 + (|x_2| - |\widehat{x}_2|)) \leq \ln(1 + |x_2 - \widehat{x}_2|), \end{aligned}$$

where, without loss of generality, we have taken  $|x_2| > |\widehat{x}_2|$ . In this case,  $\varphi_1(t) = \ln(1 + t)$  for  $t \in \mathbb{R}_+$  and it is easy to see that  $\varphi_1 \in \mathcal{A}$ .

On the other hand, for any  $x_1, x_2, \widehat{x}_1, \widehat{x}_2 \in \mathbb{R}$  and any  $t \in [0, 1]$ , we have

$$\begin{aligned} |g(t, x_1, x_2) - g(t, \widehat{x}_1, \widehat{x}_2)| &= \left| \frac{1}{10}(x_1 - \widehat{x}_1) + \frac{1}{10}(x_2 - \widehat{x}_2) \right| \\ &\leq \frac{1}{10}(|x_1 - \widehat{x}_1| + |x_2 - \widehat{x}_2|) \\ &\leq \frac{1}{5}(\max(|x_1 - \widehat{x}_1| + |x_2 - \widehat{x}_2|)) \end{aligned}$$

and, therefore, we can take  $\varphi_2(t) = \frac{1}{5}t$ . It is clear that  $\varphi_2 \in \mathcal{A}$ . Moreover,  $\varphi_1$  is obviously continuous.

Finally, the inequality appearing in assumption  $(a_3)$  of Theorem 4.12 has the form

$$\left( \ln(1 + r) + \frac{1}{2} \right) \left( \frac{1}{5}r + \frac{1}{4} \right) \leq \Gamma \left( \frac{3}{2} \right) r.$$

The last inequality is satisfied for  $r_0 = 1$ , since

$$\left( \ln 2 + \frac{1}{2} \right) \left( \frac{1}{5} + \frac{1}{4} \right) \cong 0.5373 \leq 0.88623 \cong \Gamma \left( \frac{3}{2} \right).$$

Moreover,

$$\frac{1}{5} + \frac{1}{4} = 0.45 < 0.88623 \cong \Gamma \left( \frac{3}{2} \right).$$

Now, by using Theorem 4.12, (17) has at least one solution  $x \in C[0, 1]$  such that  $\|x\| \leq 1$ .

## 6. COMPARISON WITH OTHER RESULTS

The authors in [21] studied the fractional hybrid differential equation

$$(18) \quad \begin{cases} D_{0^+}^\alpha \left[ \frac{x(t)}{f(t, x(t))} \right] = g(t, x(t)), \text{ a.e. } t \in [0, 1], \\ x(0) = 0, \end{cases}$$

under the following conditions:

- (i)  $f \in C([0, 1] \times \mathbb{R}, \mathbb{R} \setminus \{0\})$  and  $g \in C([0, 1] \times \mathbb{R}, \mathbb{R})$ .
- (ii) The function  $x \rightarrow \frac{x}{f(t, x)}$  is increasing in  $\mathbb{R}$  almost everywhere for  $t \in [0, 1]$ .
- (iii) There exists a constant  $L > 0$  such that,

$$|f(t, x) - f(t, y)| \leq L|x - y|,$$

for every  $t \in [0, 1]$  and  $x, y \in \mathbb{R}$ .

(iv) There exists a function  $h \in L^1([0, 1], \mathbb{R}_+)$  such that,

$$|g(t, x)| \leq h(t) \text{ a.e } t \in [0, 1], \text{ for all } x \in \mathbb{R}.$$

(v)  $\frac{L\|h\|_{L^1}}{\Gamma(\alpha + 1)} < 1$ .

They proved the following result.

**Theorem 6.16** (Theorem 3.1 [21]). *Under assumptions (i) – (v), (18) has a solution in  $C[0, 1]$ .*

It is easy to see that (18) is a particular case of (5) when the functions  $f(t, x, y)$  and  $g(t, x, y)$  are independent of  $y$ .

Next, we present an example which cannot be treated by using Theorem 6.16 but it can be studied by Theorem 4.12.

EXAMPLE 6.17. Consider the following fractional hybrid initial value problem

$$(19) \quad \begin{cases} D_{0+}^{\frac{1}{2}} \left[ \frac{x(t)}{\left[\frac{1}{5} + \ln(1 + |x(t)|)\right]} \right] = \frac{1}{8} + \frac{1}{10}|x(t)|, & 0 < t < 1, \\ x(0) = 0. \end{cases}$$

(19) is a particular case of (5), where  $\alpha = \frac{1}{2}$ ,  $\mu = \sigma = 0$ ,  $f(t, x, y) = \frac{1}{5} + \ln(1 + |x|)$  and  $g(t, x, y) = \frac{1}{8} + \frac{1}{10}|x|$ .

Obviously, the functions  $f$  and  $g$  satisfy assumption  $(a_1)$  of Theorem 4.12 and, moreover,  $k_1 = \sup\{|f(t, 0, 0)|\} = \frac{1}{5}$  and  $k_2 = \sup\{|g(t, 0, 0)|\} = \frac{1}{8}$ .

By using a similar argument as in Example 5.15, we obtain

$$|f(t, x_1, x_2) - f(t, \hat{x}_1, \hat{x}_2)| = |\ln(1 + |x_1|) - \ln(1 + |\hat{x}_1|)| \leq \ln(1 + |x_1 - \hat{x}_1|)$$

and

$$|g(t, x_1, x_2) - g(t, \hat{x}_1, \hat{x}_2)| = \frac{1}{10} ||x_1| - |\hat{x}_1|| \leq \frac{1}{10}|x_1 - \hat{x}_1|$$

for any  $x_1, x_2, \hat{x}_1, \hat{x}_2 \in \mathbb{R}$  and  $t \in [0, 1]$ . Therefore, the functions  $f$  and  $g$  satisfy assumption  $(a_2)$  of Theorem 4.12 with  $\varphi_1(t) = \ln(1 + t)$  for  $t \in \mathbb{R}_+$  and  $\varphi_2(t) = \frac{t}{10}$  for  $t \in \mathbb{R}_+$ . It is easy to see that  $\varphi_1, \varphi_2 \in \mathcal{A}$  and  $\varphi_1$  is continuous.

For assumption  $(a_3)$  of Theorem 4.12, we have the inequality

$$\left(\ln(1 + r) + \frac{1}{5}\right) \left(\frac{1}{10}r + \frac{1}{8}\right) \leq \Gamma\left(\frac{3}{2}\right) r$$

and this inequality is satisfied by  $r_0 = 1$ , since

$$\left(\ln 2 + \frac{1}{5}\right) \left(\frac{1}{10} + \frac{1}{8}\right) \cong 0.200958 \leq 0.88623 \cong \Gamma\left(\frac{3}{2}\right).$$

Moreover,

$$\frac{1}{10} + \frac{1}{8} \cong 0.225 < \Gamma\left(\frac{3}{2}\right) \cong 0.88623.$$

Therefore, by Theorem 4.12, (19) has a solution  $x \in C[0, 1]$  with  $\|x\| \leq 1$ .

Notice that problem (19) cannot be treated by Theorem 6.16 since the function  $g(t, x, y) = \frac{1}{8} + \frac{1}{10}|x|$  does not satisfy assumption (iv).

In [2], the authors studied the nonlinear pantograph equation, Eq.(2), under the following assumptions:

- (i)  $\alpha, \lambda \in (0, 1)$ .
- (ii)  $f : J \times X \times X \rightarrow X$  is a continuous function, where  $(X, \|\cdot\|)$  is a Banach space.
- (iii) There exists a positive constant  $L > 0$  such that

$$\|g(t, u, x) - g(t, v, y)\| \leq L(\|u - v\| + \|x - y\|),$$

for any  $t \in J$  and  $u, v, x, y \in X$ .

- (iv)  $4\gamma L < 1$ , where  $\gamma = \frac{T^\alpha}{\Gamma(\alpha + 1)}$ .

They proved the following result.

**Theorem 6.18** (Theorem 3.1 of [2]). *Under assumptions (i)–(iv), (2) has a unique solution in  $C(J \times X)$ .*

Next, we present an example which cannot be treated by Theorem 6.18 while it can be studied by Theorem 4.12.

EXAMPLE 6.19. Consider the following fractional pantograph equation

$$(20) \quad \begin{cases} D_{0+}^{\frac{1}{2}} x(t) = \frac{1}{25} + \ln\left(1 + \left|x\left(\frac{t}{2}\right)\right|\right), & 0 < t < 1, \\ x(0) = 0. \end{cases}$$

(20) is a particular case of (5), where  $\alpha = \frac{1}{2}$ ,  $f(t, x, y) = 1$ ,  $\sigma = \frac{1}{2}$  and  $g(t, x, y) = \frac{1}{25} + \ln(1 + |y|)$ .

It is clear that the functions  $f$  and  $g$  satisfy assumption  $(a_1)$  of Theorem 4.12 and, moreover,  $k_1 = \sup\{|f(t, 0, 0)| : t \in [0, 1]\} = 1$  and  $k_2 = \sup\{|g(t, 0, 0)| : t \in [0, 1]\} = \frac{1}{25}$ .

It is obvious that  $\varphi_1(t) = 0$  and if  $|y| > |y_1|$  then, by using a similar argument that in Example 5.15, we have

$$|g(t, x, y) - g(t, x_1, y_1)| = |\ln(1 + |y|) - \ln(1 + |y_1|)| \leq \ln(1 + |y - y_1|).$$

Therefore,  $\varphi_2(t) = \ln(1 + t)$  and  $\varphi_2 \in \mathcal{A}$ .

In this case, assumption  $(a_3)$  of Theorem 4.12 is given by

$$\ln(1 + r) + \frac{1}{25} \leq r\Gamma\left(\frac{3}{2}\right)$$



and it is easily seen that this inequality is satisfied by  $r_0 = 1$ , since

$$\ln 2 + \frac{1}{25} \cong 0.73344 < 0.88623 \cong \Gamma\left(\frac{3}{2}\right).$$

Therefore, by Theorem 4.12, problem (20) has a solution  $x \in [0, 1]$  with  $\|x\| \leq 1$ .

On the other hand, an application of the mean value theorem gives us

$$|g(t, x, y) - g(t, x_1, y_1)| = |\ln(1 + |y|) - \ln(1 + |y_1|)| \leq ||y| - |y_1|| \leq |y - y_1|.$$

Consequently,  $L = 1$  in assumption (iii) of Theorem 6.18.

$$\text{Moreover, } \gamma = \frac{1}{\Gamma\left(\frac{3}{2}\right)} \text{ and } 4\gamma L = \frac{4}{\Gamma\left(\frac{3}{2}\right)} = 4.51 > 1.$$

Notice that the constant  $L = 1$  cannot be improved in the last inequality since  $(\ln(1 + x))' = \frac{1}{1+x}$  for  $x \geq 0$  and  $\frac{1}{1+x}$  tends to 1 when  $x$  tends to zero.

Therefore, since  $4\gamma L = 4.51 > 1$ , problem (20) cannot be studied by Theorem 6.18.

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